

An Internet of Data Center Robotic Things for Cloud Robotics: A Concept of Data Center for a Green Environment

*

1st Dr. Rishi Kumar Sharma 2rd Dr. Rakesh Kumar Saxena
Associate Professor. CSE Professor. FCE
Jagannath Univeristy Poornima University
Jaipur, India Jaipur, India
rishi.rishi1526@gmail.com saxenark06@gmail.com

3rd Sunil Kushwaha
Assistant Professor. FCE
Poornima Univeristy
Jaipur, India
sunilkushwaha254@gmail.com

4th Mr.Bhanu Partap
Assistant Professor. CSE
Quantum University
Roorkee, India
bhanu8909@gmail.com

5th Mr.Shailendra
Sharma
Assistant Professor.
CSE
Jagannath Univeristy
Jaipur, India
ershail88@gmail.com

To Cite this Article

Dr. Rishi Kumar Sharma | Dr. Rakesh Kumar Saxena\ Sunil Kushwaha\ Mr.Bhanu Partap\ Mr.Shailendra Sharma “**An Internet of Data Center Robotic Things for Cloud Robotics: A Concept of Data Center for a Green Environment**” *Journal of Science and Technology, Vol. 09, Issue 10,-Oct 2024, pp01-06*

Article Info

Received: 27-07-2024 Revised: 06-08-2024 Accepted: 14-09-2024 Published: 24-10-2024

Abstract—As the name implies, the Internet of Data Center Robotic Things (IoDCRT) is a combination of multiple technologies, that describes how to empower a robot with intelligence to execute critical tasks by itself. It is a concept in which intelligent technology can monitor and manipulate automatically the events happening around robots. IoDCRT is a relatively new field, where autonomous machines gather data from multiple sensors and communicate with every other to perform given tasks. This new study looks at how the integration of data centers, the Internet of Things, and robotic technology will improve the capabilities of both existing robotics and allow for the development of new, potentially disruptive services. We discuss many of the new technological challenges created by this fusion and adduce that a truly holistic and real view is needed but is nowadays lacking. This paper introduces IoDCRT and its applications.

Keywords Terms—Internet of things, Distributed Robotics, Net-work robot systems, Internet of Data Center Robotic Things.

I. INTRODUCTION

A Data center-based robot is a machine that can sense its environment, perform computation for decision-making, execute the allocated tasks autonomously, and navigate from the initial to the goal position by the Robotics Data Center. In the real world, without any data center support, building a single robot to perform gigantic or complex tasks autonomously is impossible.

Therefore, multiple Robotic Data Centers of various sizes, shapes, and capabilities have been developed to accomplish complex or gigantic or multiple tasks cooperatively.

Recently Internet of Things (IoT) has apparent expeditious growth and attention for emphasizing the vision of a global infrastructure that interconnects the physical nodes called things and utilizes the same network protocol, authorizing the network to communicate and share data and information. Therefore, the technology of IoT is being implemented in various fields, such as robotics, military, nanotechnology, healthcare or space, customer service, environmental monitoring, smart home, and creating the internet of X things, where X is the relevant area.

II. CLOUD COMPUTING

Cloud computing is a model that combines "Cloud" and "Computing Resources" to deliver computing services over the internet. The term "Cloud" refers to a network of remote servers hosted on the internet that store and manage data, as opposed to local servers or personal computers. These servers are often maintained by third-party providers like Amazon Web Services (AWS), Microsoft Azure, or Google Cloud.

Cloud Computing=Cloud+ Computing Resources "Computing Resources" encompass the various components required to perform computing tasks. This includes processing power (CPUs), memory (RAM), storage (hard drives or SSDs), and networking capabilities. In a traditional computing environment, businesses and individuals need to invest in and maintain physical hardware for these resources.

With cloud computing, these resources are provided as a service by cloud providers. Users can access and scale these resources on-demand without having to own or manage the underlying hardware. This model offers flexibility, scalability, and cost-efficiency, as users only pay for what they use and can easily adjust their resources based on current needs. Cloud computing enables innovation and agility by providing access to powerful computing capabilities without the constraints of physical infrastructure.

INTERNET OF THINGS

The Internet of Things (IoT) refers to the network of inter-connected devices that communicate and exchange data over the Internet. These devices, embedded with sensors, software, and other technologies, collect and share information to create a smart, automated system. Examples include smart home IoT devices like thermostats and security cameras, wearable fitness trackers, and industrial sensors. IoT enhances efficiency and convenience by enabling real-time monitoring and control, allowing systems to respond automatically to changing conditions or user inputs. This interconnected ecosystem facilitates data-driven decision-making and seamless integration across various applications.

IV. ROBOTICS

Robotics involves the design, construction, and operation of robots—machines capable of carrying out tasks autonomously or semi-autonomously. Robots are equipped with sensors, actuators, and control systems that enable them to execute actions and make decisions based on environmental data. They can be used in various fields, from manufacturing and health-care to exploration and service industries. Robotics integrates principles from engineering, computer science, and artificial intelligence to create machines that can handle complex tasks, improve efficiency, and interact with their surroundings in meaningful ways.

V. CLOUD ROBOTICS

Cloud robotics is an advanced concept that merges cloud computing resources with networked robotics, creating a powerful synergy that enhances robotic capabilities. In this framework, "Cloud Computing Resources" refers to the extensive computational power, storage, and processing abilities provided by cloud services over the internet. These resources enable robots to execute complex tasks by offloading heavy computational workloads and storing large volumes of data on remote servers.

Cloud Robotics= Cloud Resources + Network Robotics On the other hand, "Networked Robotics" pertains to the integration of robots into a network, allowing them to communicate and collaborate with central systems. This connectivity allows robots to share information, learn from collective experiences, and coordinate their actions more effectively.

By combining cloud computing with networked robotics, robots can leverage cloud-based algorithms and data to improve their performance and adaptability. For instance, they can access advanced machine learning models for better decision-making or receive real-time updates and instructions from a centralized cloud platform. This integration enhances the scalability, flexibility, and intelligence of cloud robotic systems, enabling them to tackle more complicated tasks and operate more efficiently in diverse environments.

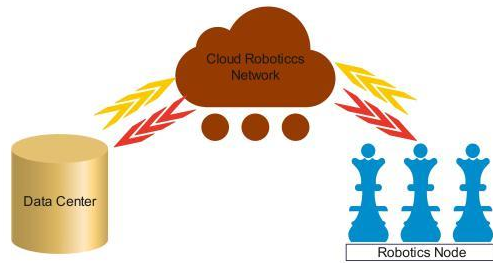


Fig. 1. CLOUD ROBOTICS

VI. INTERNET OF ROBOTIC THINGS

The Internet of Robotic Things (IoRT) is an advanced concept that combines the Internet of Things (IoT) with robotics to create an intelligent network of interconnected robots. In IoRT, robots are equipped with sensors, communication modules, and computing capabilities that enable them to connect to the internet and interact with other devices and systems. This connectivity allows robots to gather and share data, communicate with other robots, and receive real-time updates or commands from centralized systems.

The integration of IoT with robotics enhances the functionality and effectiveness of robotic systems. For example, robots can access and analyze vast amounts of data from various sources to make more informed decisions. They can also collaborate with other robots and IoT-enabled devices to perform complex tasks more efficiently. This interconnected ecosystem enables more sophisticated automation and coordination, improving operational efficiency and responsiveness.

In practical terms, IoRT can be seen in smart factories where robots work alongside IoT sensors to optimize manufacturing processes or in smart homes where robotic assistants interact with other smart devices to provide personalized services. By leveraging the strengths of both IoT and robotics, IoRT creates a more dynamic and intelligent environment for automation and data-driven decision-making.

VII. ARTIFICIAL GENERAL INTELLIGENCE

Artificial General Intelligence (AGI) refers to a level of artificial intelligence that possesses the capability to understand, learn, and apply knowledge across a broad range of tasks at a level comparable to human cognitive abilities. Unlike Narrow AI, which is designed for specific tasks such as language translation and image recognition, AGI is designed to exhibit general intelligence, meaning it can perform any intellectual task that a human can.

AGI would involve the development of machines that not only excel in predefined tasks but also adapt to new and unforeseen situations with the flexibility and creativity of human intelligence. This includes capabilities such as reasoning, problem-solving, understanding complex concepts, and learning from experience. AGI aims to replicate human-like cognitive functions, including self-awareness, common sense, and the capability to transfer knowledge across many domains.

The pursuit of AGI raises significant technical, ethical, and philosophical questions. Developing such a system requires breakthroughs in multiple areas, including machine learning, cognitive science, and neuroscience. The impact of AGI could be profound, potentially revolutionizing industries, challenging existing notions of consciousness, and raising important ethical considerations about control, autonomy, and the future of human-machine interaction.

VIII. INTERNET OF DATA CENTER ROBOTIC THINGS

Internet of Data Center Robotic Things for Cloud Robotics (IoDCRTR) is a sophisticated concept that integrates data center operations with advanced robotic systems through cloud computing. This approach envisions a network where robots within data centers are interconnected and managed via cloud-based platforms, enhancing efficiency and automation in data handling and infrastructure management.

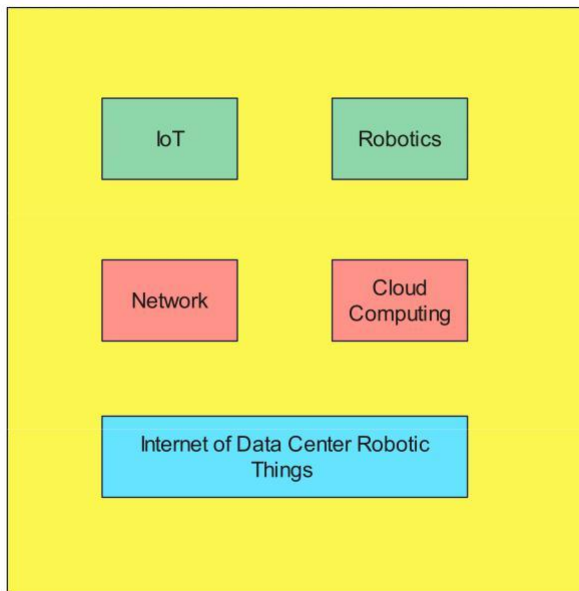


Fig. 2. INTERNET OF DATA CENTER ROBOTIC THINGS

In this framework, data center robots are furnished with sensors and communication tools that allow them to interact with cloud systems and other networked robots. The cloud provides a centralized hub for data processing, analytics, and control, enabling real-time monitoring and coordination of robotic activities. This setup allows robots to perform complex tasks such as equipment maintenance, server management, and data storage optimization autonomously or with minimal human intervention.

By leveraging cloud computing resources, IoDCRTR enables scalable, flexible, and intelligent management of data centers. Robots can access and analyze large volumes of data from cloud-based analytics to optimize their operations, predict maintenance needs, and improve overall performance. Additionally, cloud integration facilitates seamless updates and adaptations to evolving data center requirements. This synergy enhances operational efficiency, reduces downtime, and supports the dynamic demands of modern data center environments.

IX. INTERNET OF DATA CENTER ROBOTIC THINGS FOR CLOUD ROBOTICS IN A GREEN ENVIRONMENT

Internet of Data Center Robotic Things for Cloud Robotics in a Green Environment (IoDCR-GE) is a cutting-edge concept that combines the power of cloud robotics and inter-connected data center robots with a focus on sustainability and environmental efficiency. This concept aims to transform data centers into eco-friendly hubs by leveraging advanced robotics and cloud computing to optimize energy usage, reduce waste, and minimize the environmental footprint.

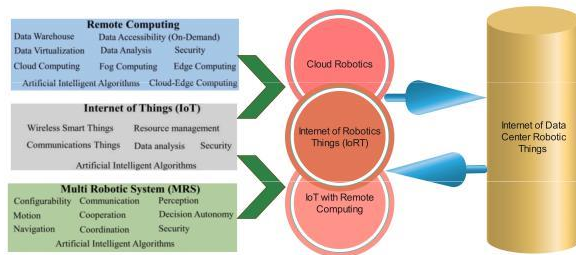


Fig. 3. Internet of Data Center Robotic Things for Cloud Robotics

In IoDCR-GE, robots within data centers are connected through a cloud-based network that allows for real-time monitoring and intelligent management of resources. These robots are furnished with sensors and AI-driven systems that can autonomously perform tasks such as optimizing cooling systems, managing energy consumption, and monitoring environmental conditions. The cloud platform facilitates data aggregation and analysis, enabling predictive maintenance and operational adjustments to enhance energy efficiency.

By integrating green technologies, such as energy-efficient cooling solutions and renewable energy sources, with robotic automation, IoDCR-GE helps data centers significantly reduce their carbon footprint. The synergy between cloud computing and robotics ensures that data centers operate at peak efficiency, with minimal waste and environmental impact. This approach not only promotes sustainability but also sets a new standard for eco-friendly data center management in the digital age.

X. CONCLUSION

The Internet of Data Center Robotic Things (IoDCRT) represents a transformative fusion of robotics, data center management, and the Internet of Things. By empowering robots with advanced intelligence and autonomous capabilities, IoD-CRT enhances their ability to monitor and manage complex environments efficiently. This emerging field promises to drive significant advancements and innovative services across various sectors. However, it also introduces new technological challenges that require a comprehensive, integrated approach. Understanding and addressing these challenges will be crucial for realizing the full potential of IoDCRT, leading to more capable and disruptive robotic systems in the future.

REFERENCES

- [1] S.L. Anderson, Asimov's "three laws of robotics" and machine metaethics, *AI Soc.* 22 (4) (2008) 477–493.
- [2] R.N. Darmanin, M.K. Bugeja, A review on multi-robot systems categorized by application domain, in: 2017 25th Mediterranean Conference on Control and Automation (MED), IEEE, 2017, pp. 701–706.
- [3] A. Khamis, A. Hussein, A. Elmogy, Multi-robot task allocation: a review of the state-of-the-art, *Cooperative Robots Sens. Netw.* 2015 (2015) 31–51.
- [4] D. Fox, W. Burgard, H. Kruppa, S. Thrun, A probabilistic approach to collaborative multi-robot localization, *Auton. Robots* 8 (3) (2000) 325–344.
- [5] S.I. Roumeliotis, G.A. Bekey, Distributed multirobot localization, *IEEE Trans. Robot. Autom.* 18 (5) (2002) 781–795.
- [6] J. Cortes, M. Egerstedt, Coordinated control of multi-robot systems: a survey, *SICE J. Control Meas. Syst. Integr.* 10 (6) (2017) 495–503.
- [7] S.S. Anjum, R.M. Noor, M.H. Anisi, Review on manet based communication for search and rescue operations, *Wirel. Pers. Commun.* 94 (1) (2017) 31–52.

- [8] ousi N, Koukas S, Michalos G, et al. Service oriented architecture for dynamic scheduling of mobile robots for material supply. *Procedia CIRP* 2016; 55: 18–22.
- [9] Mezghani E, Exposito E and Drira K. A model-driven methodology for the design of autonomic and cognitive IoT-based systems: application to healthcare. *IEEE Trans Emerg Topics Comput Intell* 2017; 1(3): 224–234.
- [10] S. Yu, C. Fu, A.K. Gostar, M. Hu, A review on map-merging methods for typical map types in multiple-ground-robot slam solutions, *Sensors* 20 (23) (2020) 6988.
- [11] Y. Wu, X. Ren, H. Zhou, Y. Wang, X. Yi, A survey on multi-robot coordination in electromagnetic adversarial environment: challenges and techniques, *IEEE Access* 8 (2020) 53484–53497.
- [12] Dr. Rishi Kumar Sharma, “Cloud Robotics Cybersecurity: A Novel Survey on Cloud-Based Robotic Platform for Network Security”, *Robotics eJournal SSRN ELSEVIER*, 2023.
- [13] Dr. Rishi Kumar Sharma, “Prospects and Potential Impacts of Cloud Robotics In Improving Agricultural Farm Produce: A Case of India” ,*JJIEMR, International ELSEVIER SSRN*, 2024.